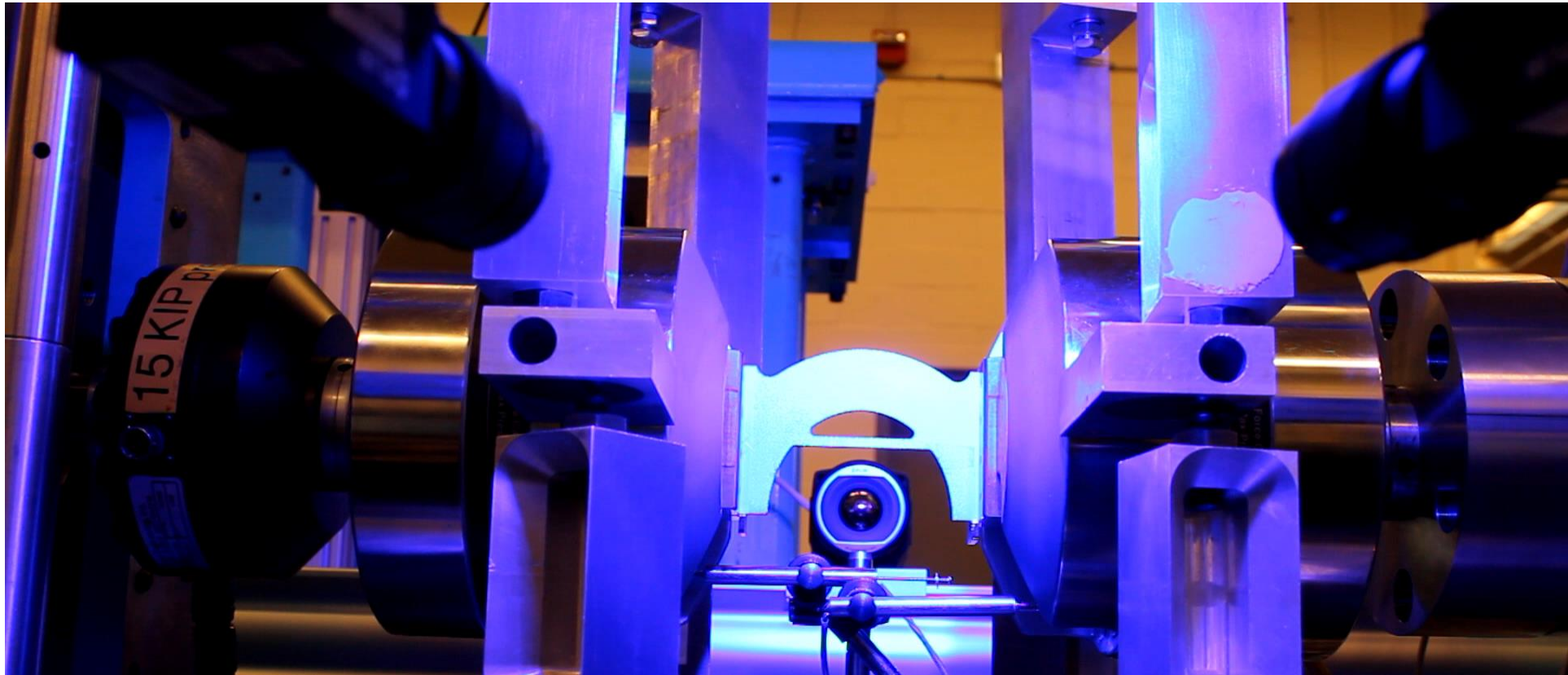


# CHAPTER 4: EXECUTION OF THE TEST



## Review all data acquisition systems

- ▶ Correct file name, location, storage capacity for DIC images
- ▶ Correct test procedure or macro
- ▶ Force signals and other measurement signals are set to record and are synchronized with DIC images
- ▶ Triggering of the test frame and/or DIC images is ready
  - ▶ **Caution 4.1:** Ensure at least one image is acquired of the test piece prior to any applied force or displacement.
- ▶ Lights are turned on, exposure is correct, and frame rate is correct



# CHAPTER 5: PROCESSING OF DIC IMAGES

SEC. 5.1: DIC SOFTWARE


SEC. 5.2: USER-DEFINED PARAMETERS



# DIC Software

## Sec. 5.1

- ▶ Both commercially and open source codes are available
- ▶ <https://idics.org/resources/>
- ▶ Speak with vendors at the conference



**Commercial DIC Software**

Follow the links below to commercial DIC software vendors for more information

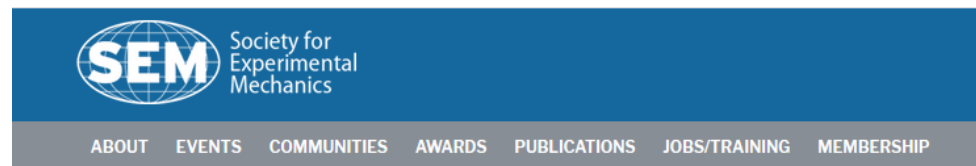
- Correlated Solutions
- EikoSim
- gom
- LaVision
- MatchID

**Research DIC Codes**

Non-commercial or open source DIC software

- AL-DIC and AL-DVC
- Digital Image Correlation Engine (DICE)
- Ncorr
- UFreckles
- YADICS

- ▶ The DIC Challenge provides vetted images
- ▶ <https://sem.org/dic-challenge/>
- ▶ PL Reu, et al., *Exp. Mech.* (2018) 58:1067-1099
- ▶ Standardized images facilitate:
  - ▶ Exploring the “black box” of proprietary/commercial DIC software
  - ▶ Verifying custom software implementations



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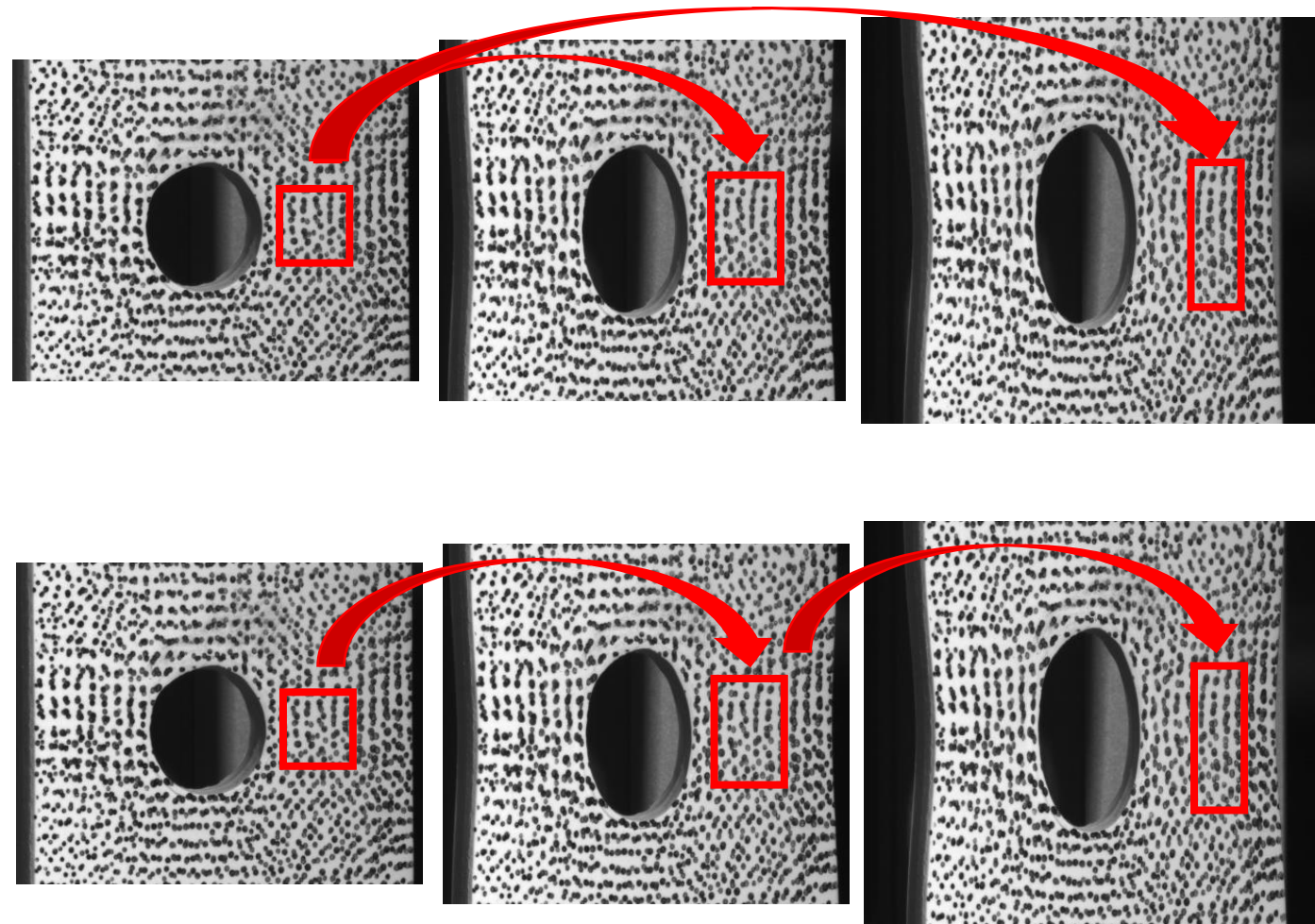
## CHALLENGE DATASET: 3D-DIC

The table below contains sample sets and a brief description. For most sets the file name or order of the data will make the imposed displacement or strain obvious. Comments can be forwarded to the board ([phillip.reu.dic@gmail.com](mailto:phillip.reu.dic@gmail.com)).

## Reference Image

### Sec. 5.2.1

- ▶ DIC tracks motion, in the Lagrangian sense, of a set of interrogation points, defined on a reference image:
- ▶ **Standard Correlation: A single reference image**
  - ▶ **Caution 5.1:** Collect reference image prior to any displacement or force
  - ▶ **Tip 5.1:** You can collect several (e.g. 10) images of stationary test piece and average, creating an approximately noise-free reference
- ▶ **Incremental Correlation**
  - ▶ Each image is correlated to prior image with the drawback of higher error
- ▶ **Partitioned correlation**
  - ▶ A test series is broken into sub-series and each batch is correlated back to the first image in that sub-series



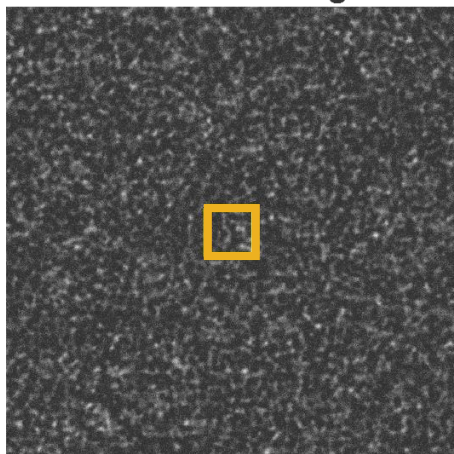


## Correlation example: Reference image

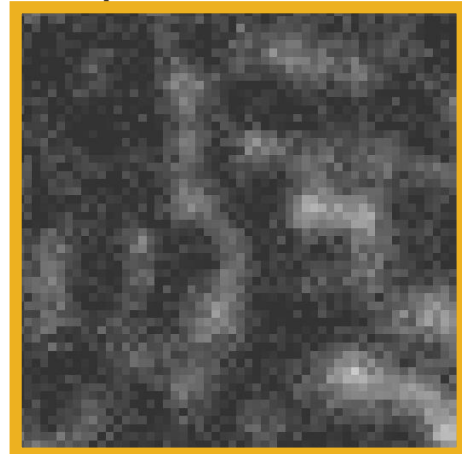
### ► *DIC Challenge Sample 2*

- Rigid translation
- Low signal/noise ratio

Reference Image

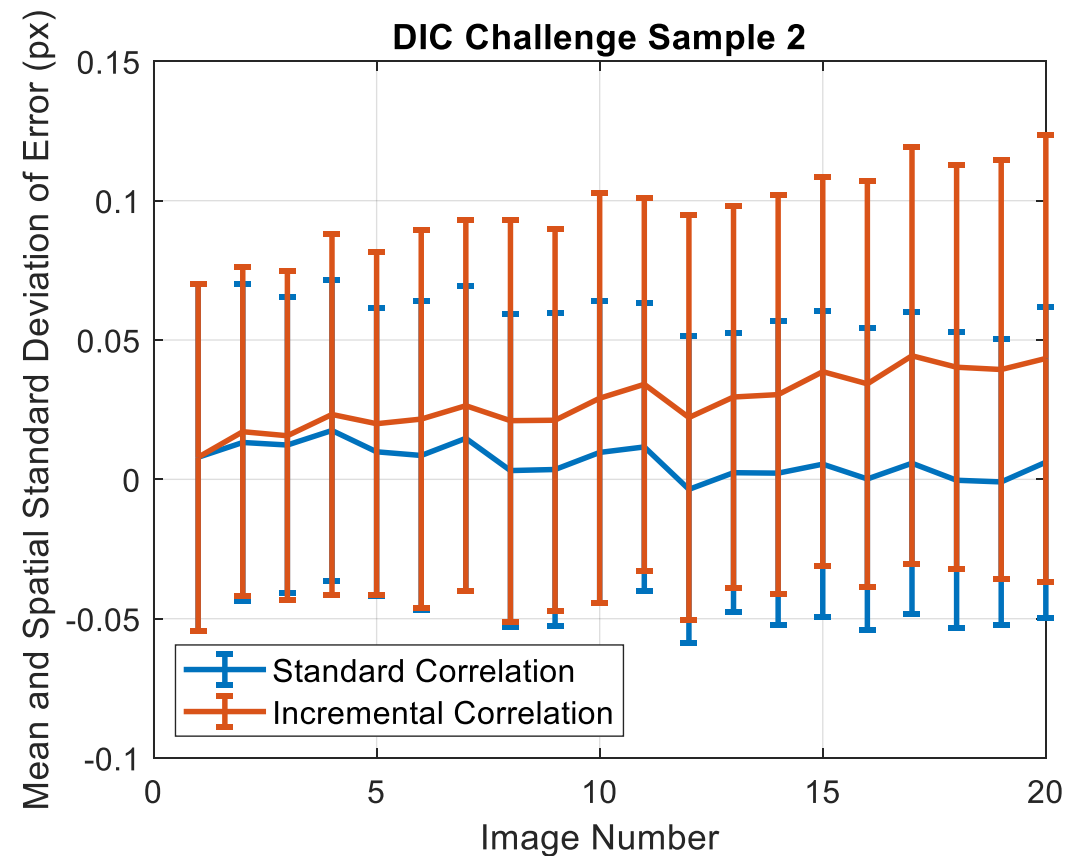


Representative Subset



### ► *Correlation parameters*

- Gaussian image prefilter with kernel size 5 px
- Affine shape function
- Bicubic spline interpolant
- ZNSSD matching criterion
- Subset size 55
- Step size 20 (529 points total)



**Noise is higher and mean error accumulates over time/image number with incremental correlation.**

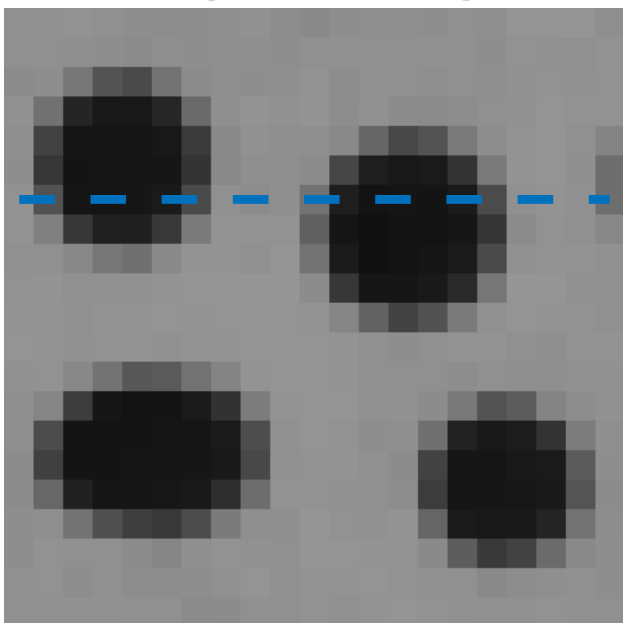
## Pre-Filtering of Images

### Sec. 5.2.2

- ▶ Subset interpolants often perform better with smooth spatial gradients in image intensity (e.g. Gaussian low pass filter)
- ▶ Low pass filter can also reduce image noise and effects of aliased features
- ▶ **Caution 5.2:** Low-pass filters can also bias the results

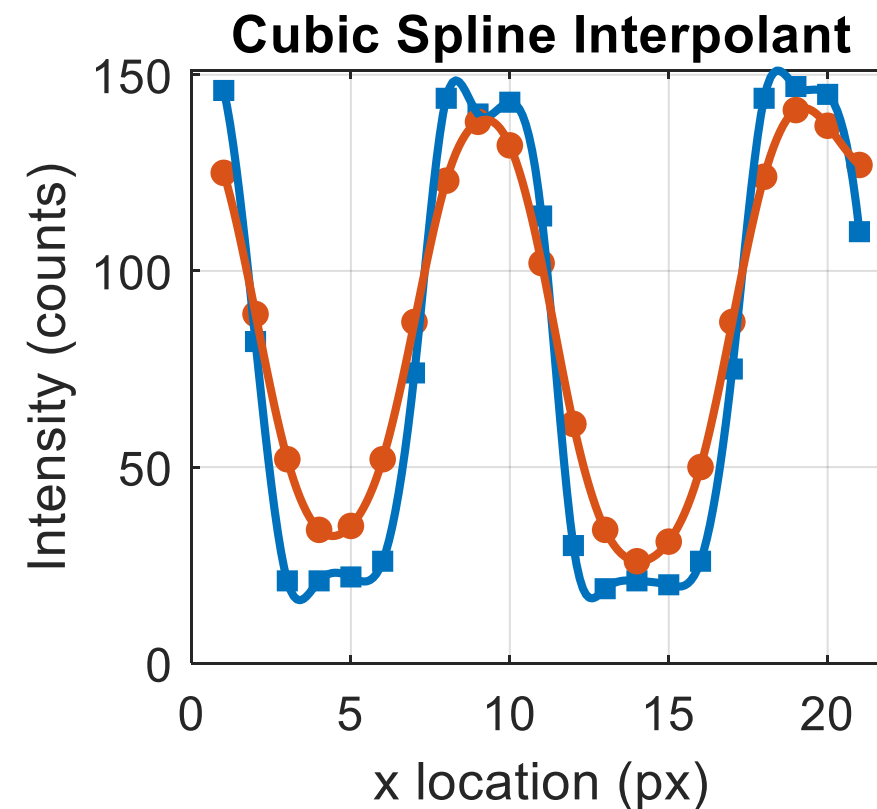
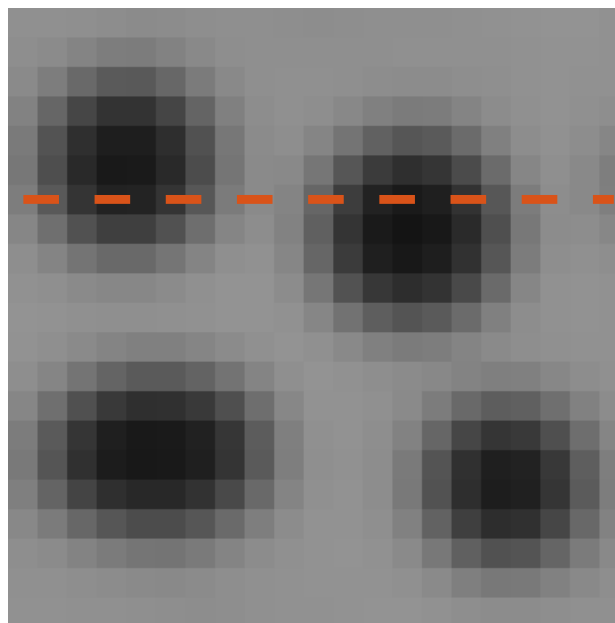
### DIC Challenge Sample 6

#### Original Image



#### Gaussian Filter

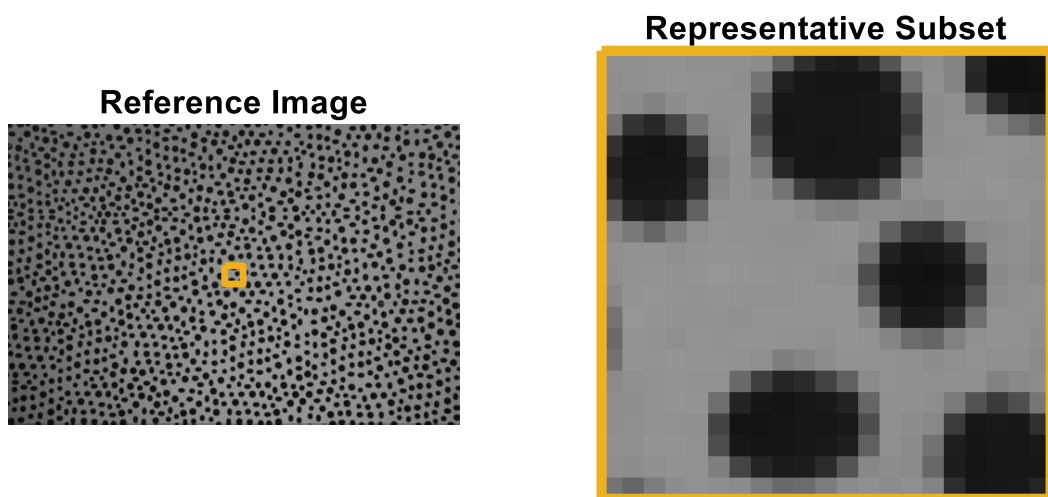
#### Kernel 5 px; STD 1 px



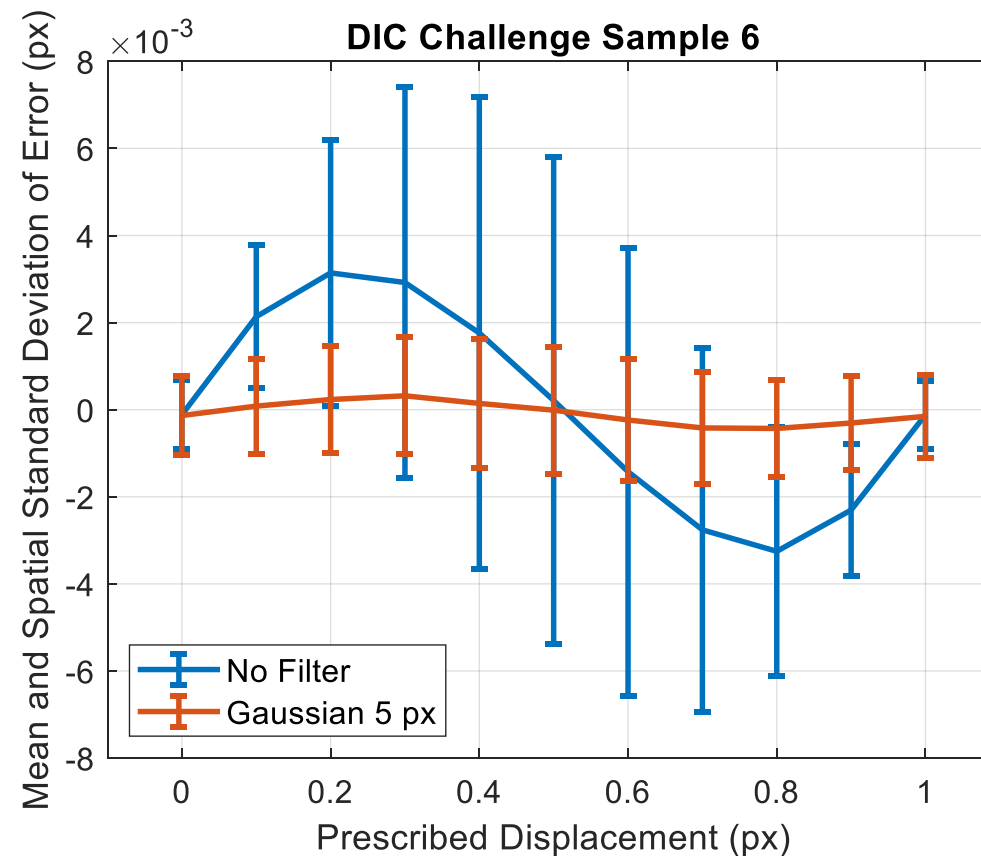


## Correlation example: Pre-filtering

- ▶ **DIC Challenge Sample 6**
  - ▶ Rigid translation in sub-pixel increments
  - ▶ Sharp-edged speckles



- ▶ **Correlation parameters**
  - ▶ Affine shape function
  - ▶ Bicubic spline interpolant
  - ▶ ZNSSD matching criterion
  - ▶ Subset size 21
  - ▶ Step size 5 (5594 points total)

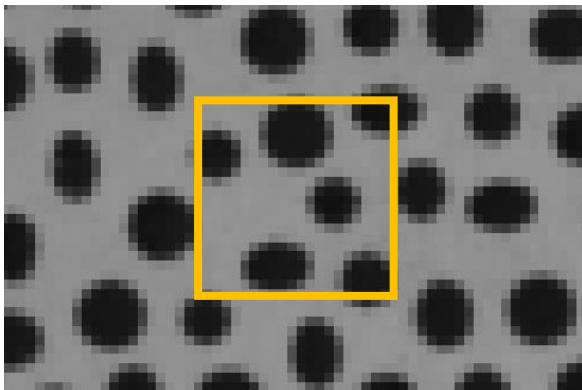


**Image prefiltering reduces both bias and variance errors.**

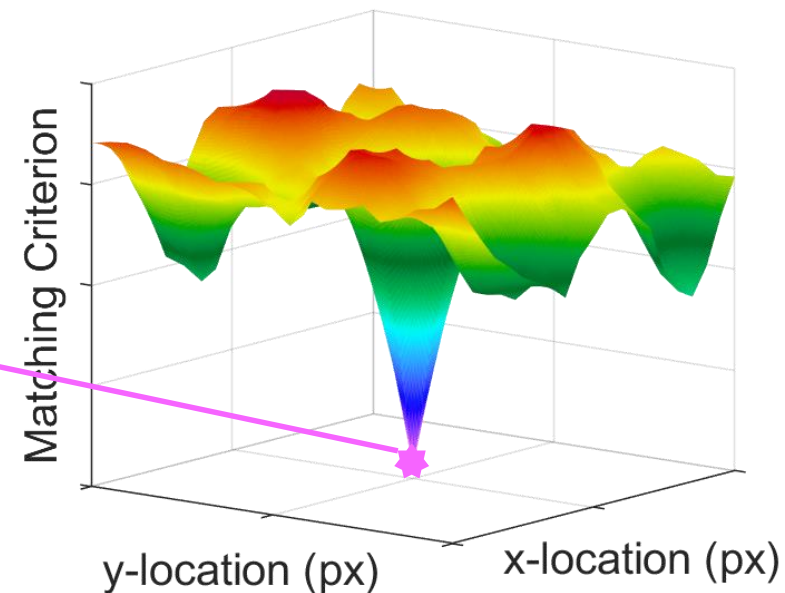
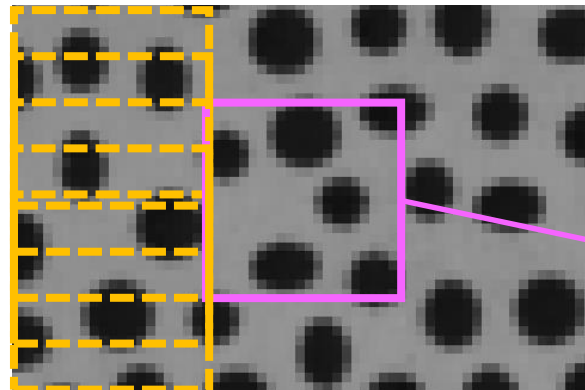


# Matching criterion Not in the guide!

Subset to find (reference image)



ROI (deformed image)



$$\chi^2 = \sum_i (G_i - F_i)^2$$

$\chi$  – is the value of the matching criterion

$F$  – is the reference image

$G$  – is the deformed image

$i$  – is the pixel in the subset

## Examples of Matching Criteria

1. Sum Squared Difference (SSD)
2. Normalized Sum Squared Difference (NSSD)
3. Zero Normalized Sum Squared Difference (ZNSSD)

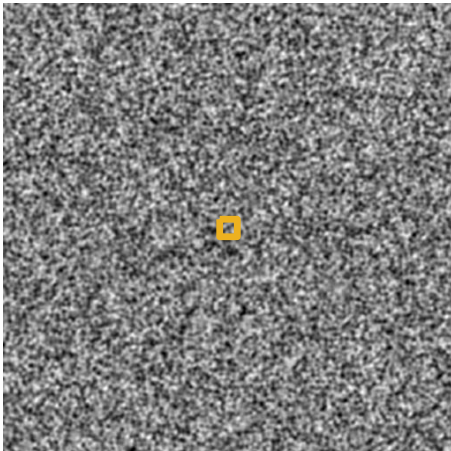


## Correlation example: Matching criterion

### ► DIC Challenge Sample 1

- Rigid translation
- Varying intensity and contrast

Reference Image

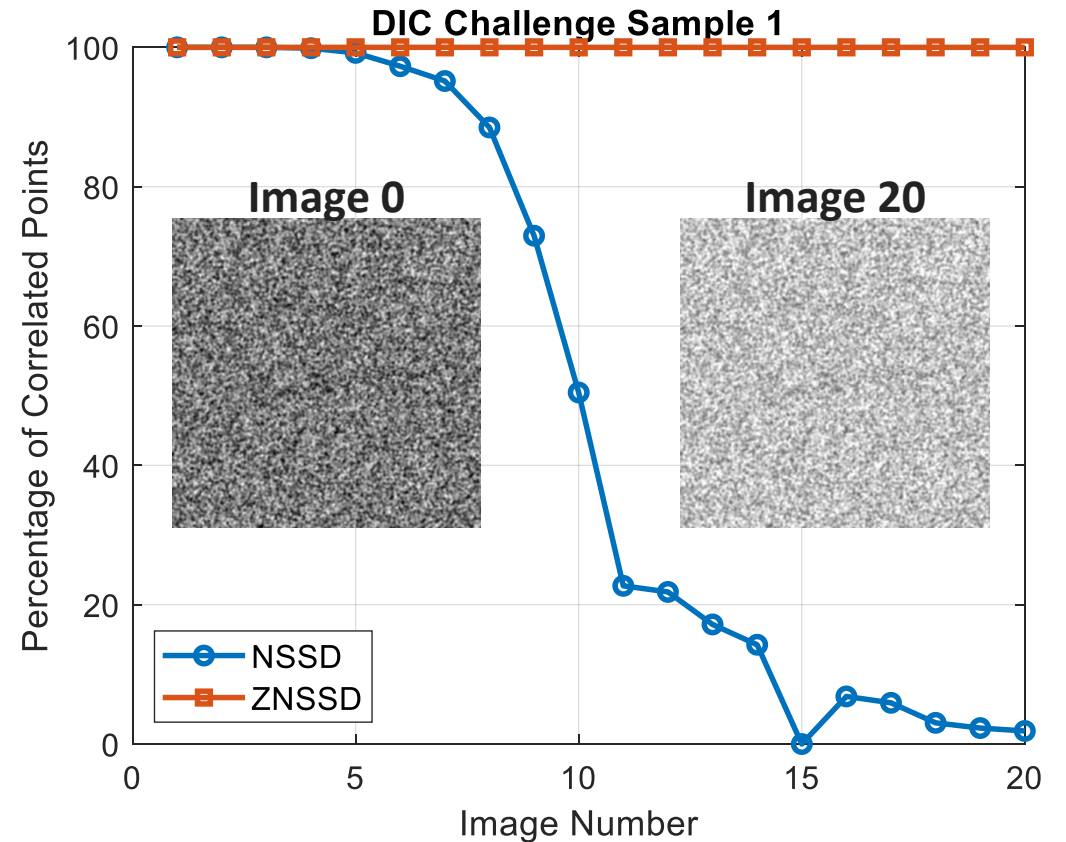


Representative Subset



### ► Correlation parameters

- Gaussian image prefilter with kernel size 5 px
- Affine shape function
- Bicubic spline interpolant
- Single reference image
- Subset size 21
- Step size 10 (2402 points total)

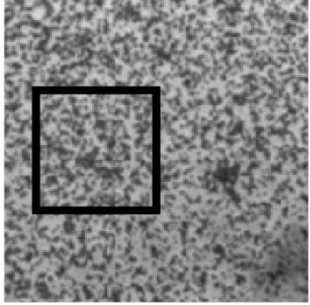


**Only the ZNSSD matching criterion is able to compensate for the varying intensity and contrast.**

# Subset Shape Function

## Sec. 5.2.3

Reference image,  $F$



$$\chi^2 = \sum_i (G_i(\xi) - F_i)^2$$

$\chi$  – is the value of the matching criterion

$F$  – is the reference image

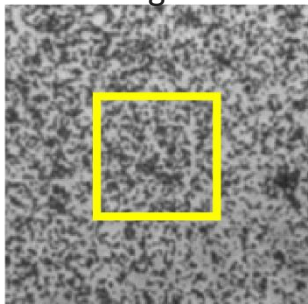
$G$  – is the deformed image

$i$  – is the pixel in the subset

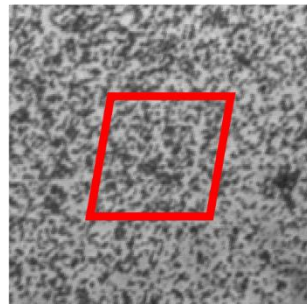
$\xi$  – is the subset shape function

$$\xi = \underbrace{\begin{bmatrix} x \\ y \end{bmatrix}}_{\text{Rigid}} + \underbrace{\begin{bmatrix} u \\ v \end{bmatrix}}_{\text{Affine}} + \underbrace{\begin{bmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix}}_{\text{Irregular}} + \underbrace{\begin{bmatrix} \frac{\partial^2 u}{\partial x \partial y} \\ \frac{\partial^2 v}{\partial x \partial y} \end{bmatrix} \Delta x \Delta y + \begin{bmatrix} \frac{\partial^2 u}{\partial x^2} & \frac{\partial^2 u}{\partial y^2} \\ \frac{\partial^2 v}{\partial x^2} & \frac{\partial^2 v}{\partial y^2} \end{bmatrix} + \begin{bmatrix} (\Delta x)^2 \\ (\Delta y)^2 \end{bmatrix}}_{\text{Quadratic}}$$

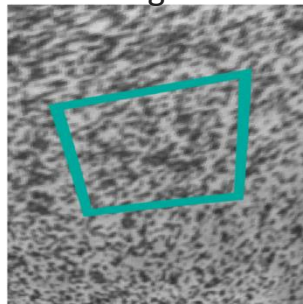
Rigid



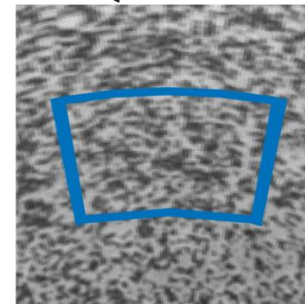
Affine



Irregular



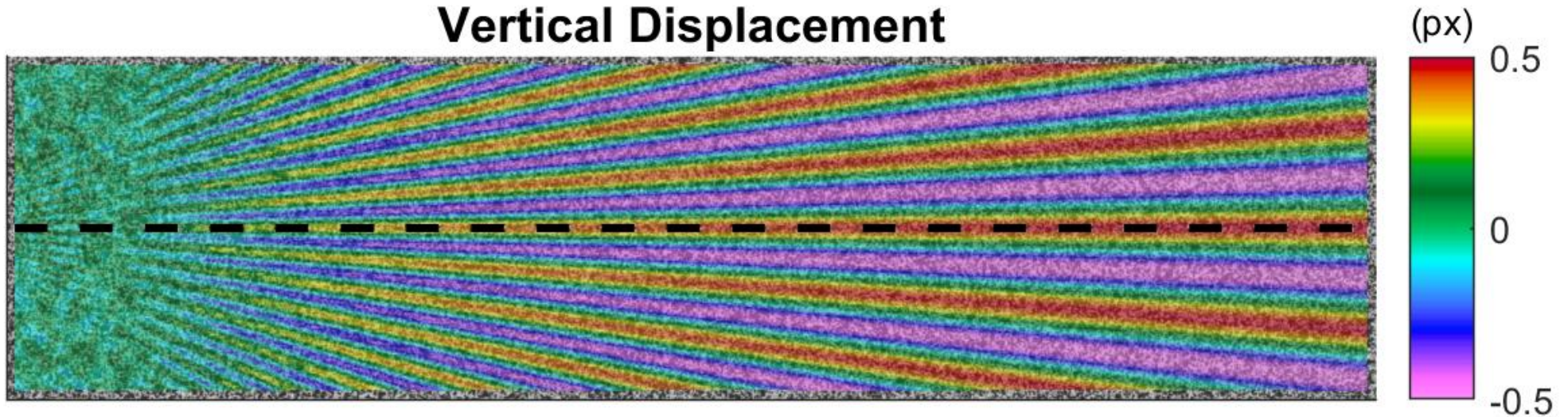
Quadratic



- ▶ Lower order shape functions cancel more noise, but have less accuracy
- ▶ Higher order shape functions are more accurate, but more noisy
- ▶ Some software packages have adaptive shape functions

## Correlation example: Subset shape function

### DIC Challenge 2.0 Star Image Vertical Displacement



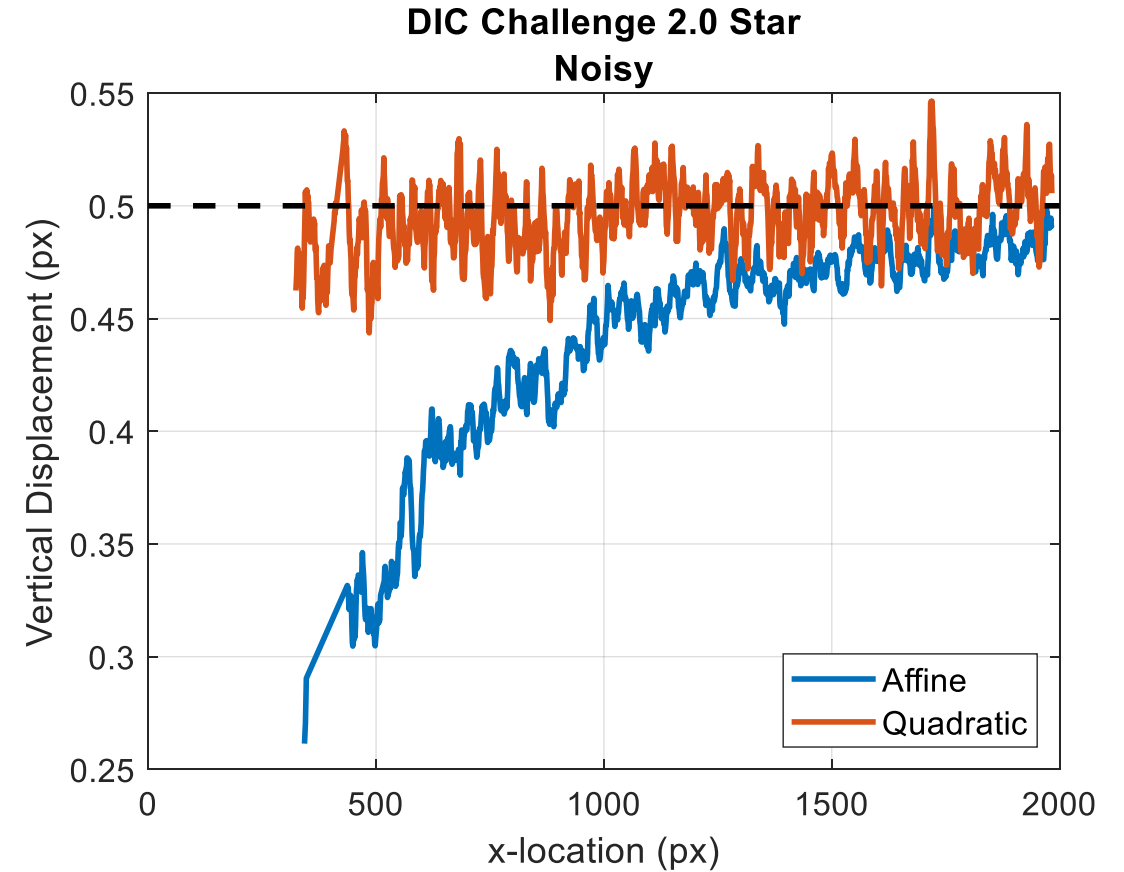
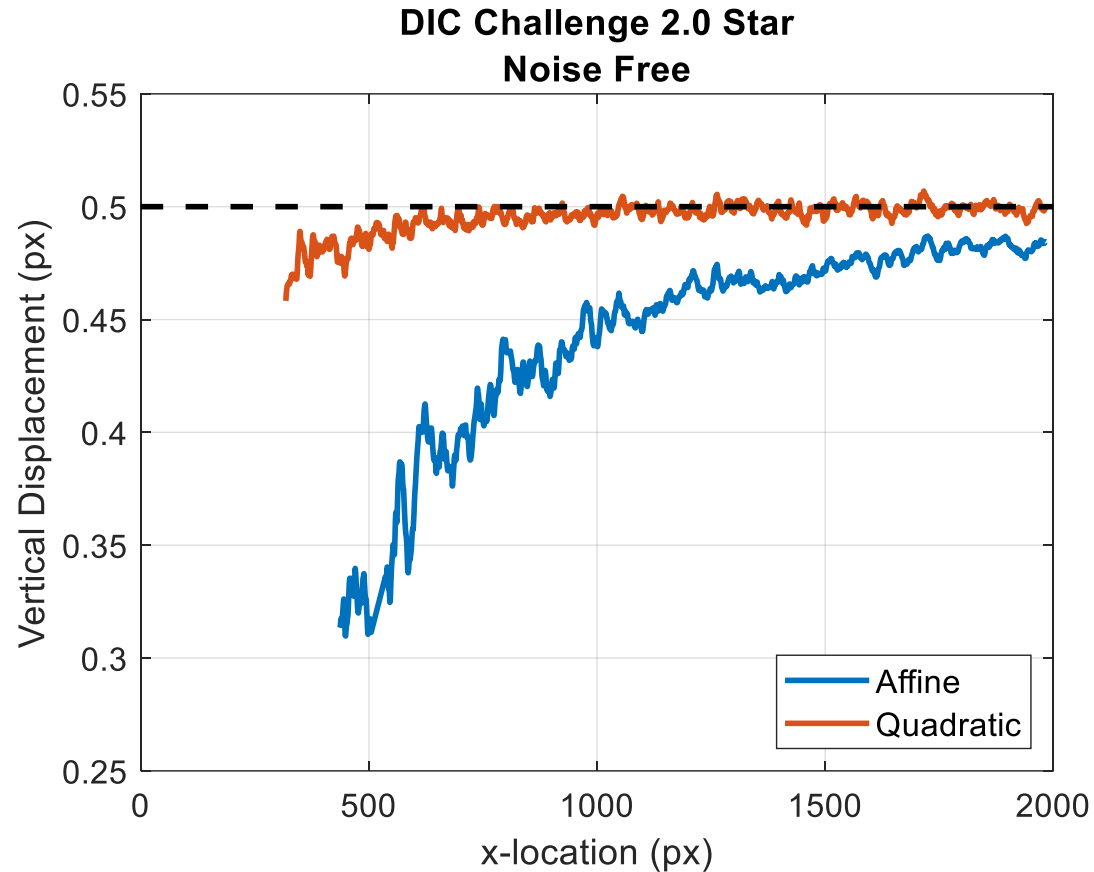
- ▶ Prescribed vertical displacement is sinusoidal
- ▶ Large period / low frequency on the right side
- ▶ Small period / high frequency on the left side
- ▶ Constant amplitude of 0.5 px along the horizontal center line cut
- ▶ Amplitude attenuated on left as shape function is inadequate to represent underlying deformation

#### *Correlation Parameters*

- ▶ No prefiltering
- ▶ Bicubic spline interpolant
- ▶ Subset size 21
- ▶ Step size 1



## Correlation example: Subset shape function



**Quadratic shape function provides better spatial resolution, but is more susceptible to image noise.**



### Interpolation allows for subpixel precision

#### Types of interpolants

1. Linear (*bad*)
2. Cubic Polynomial (*bad*)
3. Cubic Spline
4. Fourier Transform
5. Optimized filter (4-Tap, etc.)

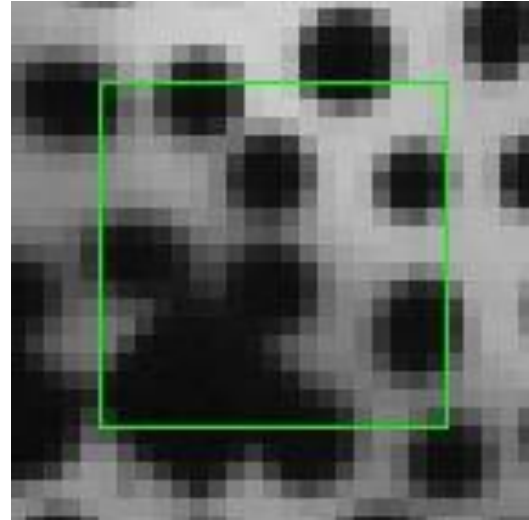
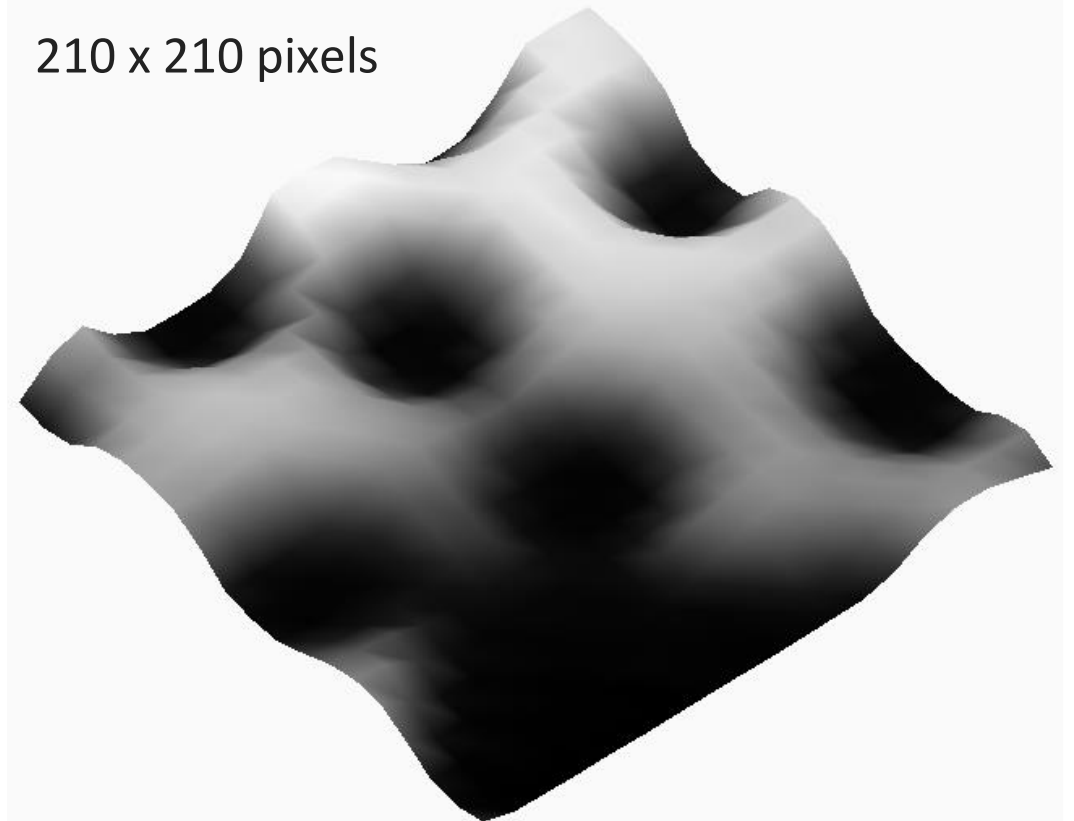
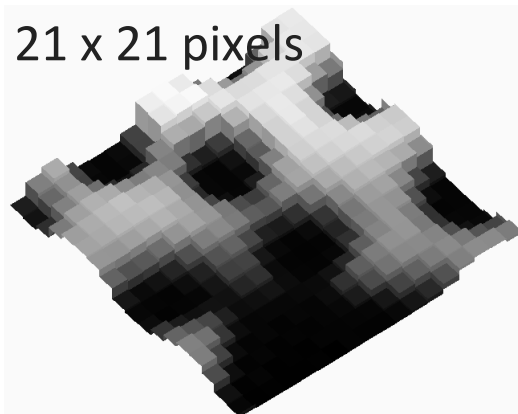


Image interpolated by a factor of 10x

210 x 210 pixels



21 x 21 pixels

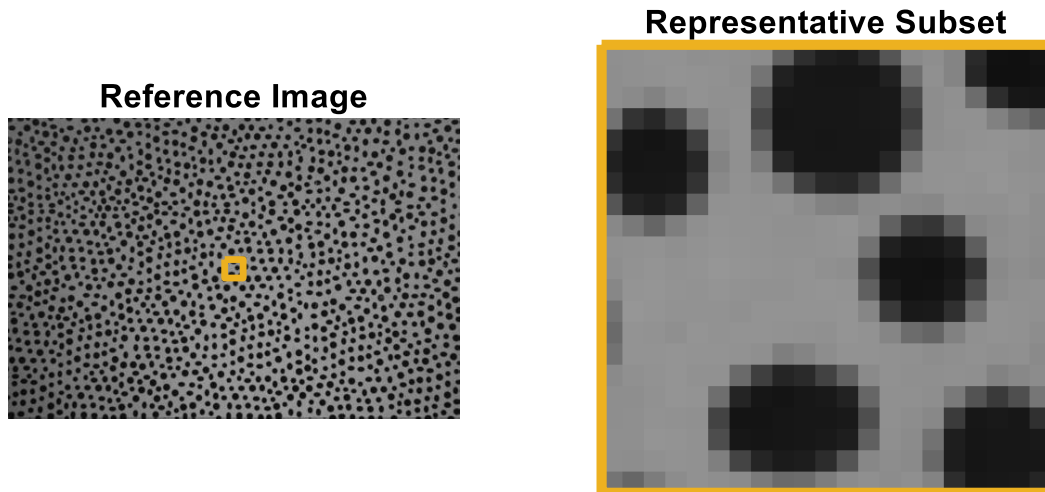


**Most commercial software packages have optimized interpolants for use!**

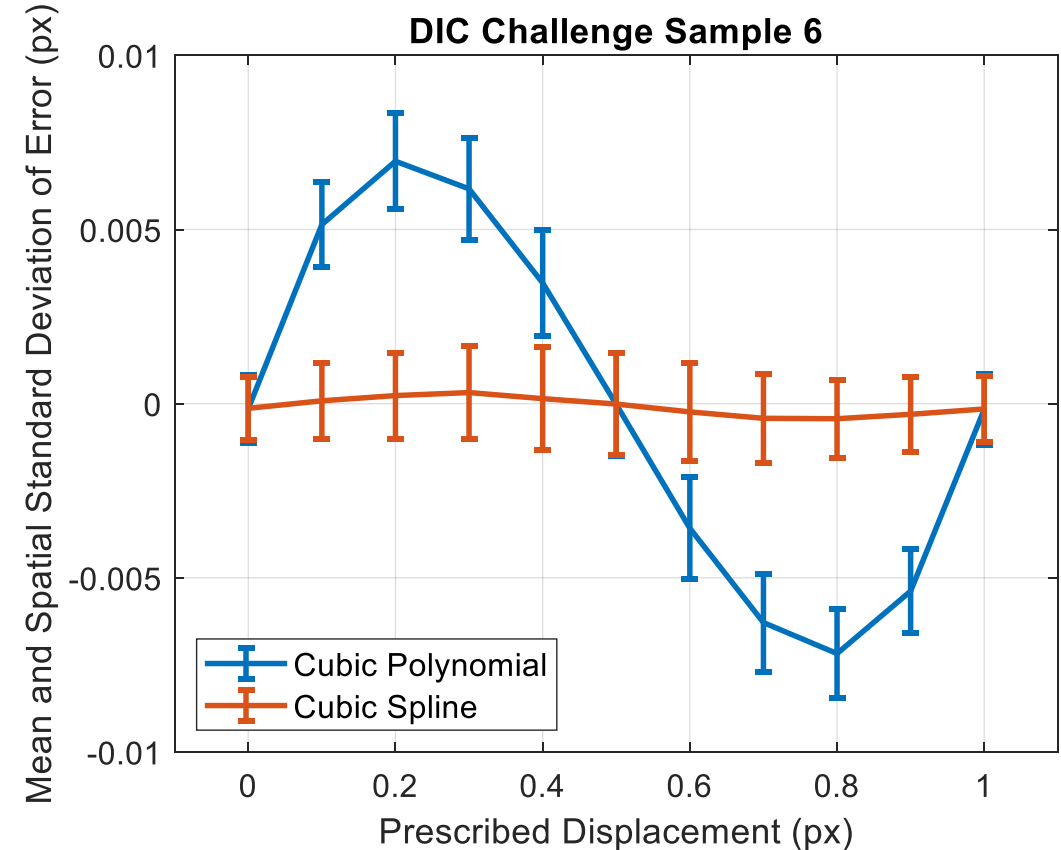


## Correlation example: Interpolant

- ▶ **DIC Challenge Sample 6**
  - ▶ Subpixel translation in x and y



- ▶ **Correlation parameters**
  - ▶ Gaussian image prefilter with kernel size 5 px
  - ▶ Affine shape function
  - ▶ Single reference image
  - ▶ Subset size 21
  - ▶ Step size 5 (5590 points total)



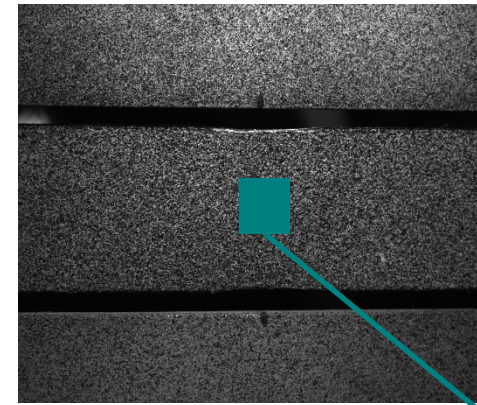
**The bi-cubic spline has much less bias than the bi-cubic polynomial.**

Use these images to evaluate interpolants in your software.

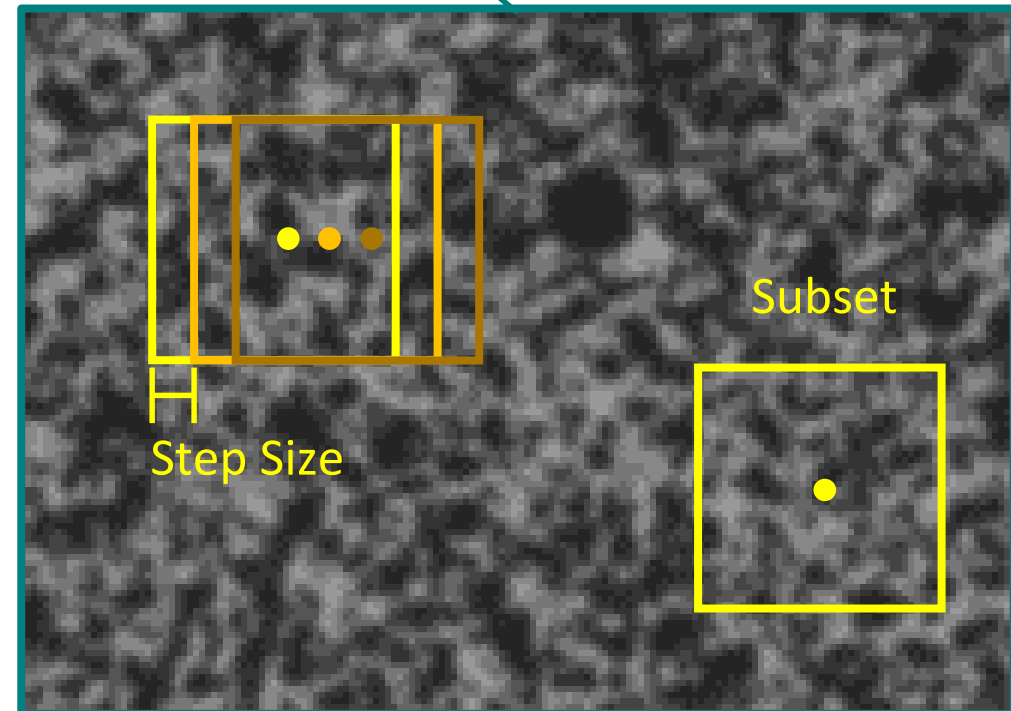
# Subset Size and Step Size

## Sec. 5.2.5-5.2.6

- ▶ **Subset:** Portion of image used to calculate one 3D coordinate or displacement value
- ▶ **Subset Size:** Length of the subset in the reference image
- ▶ **Rules of thumb:**
  1. Subset should contain a minimum of 3 DIC pattern features that are each 3-5 pixels in size
  2. Subset size should be large enough to allow “adequate correlation” for all images in the test series
  3. Subset size should be large enough to minimize correlation error metric
- ▶ **Step Size:** Spacing at which subset displacements are calculated
- ▶ **Rules of thumb:**
  - ▶ 1/3 to 1/2 of the subset size is recommended
  - ▶ May need smaller step size to capture peaks



Reference  
Image



Subset

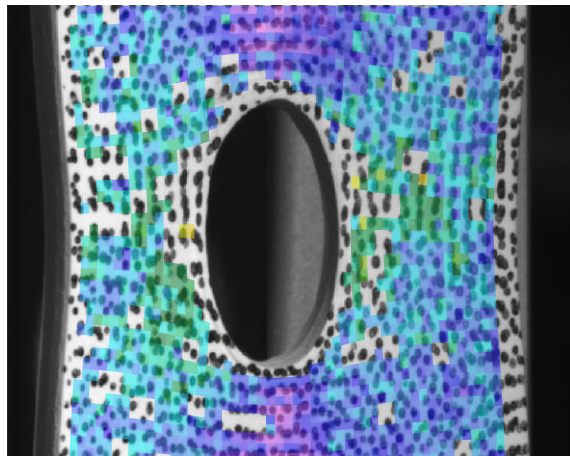
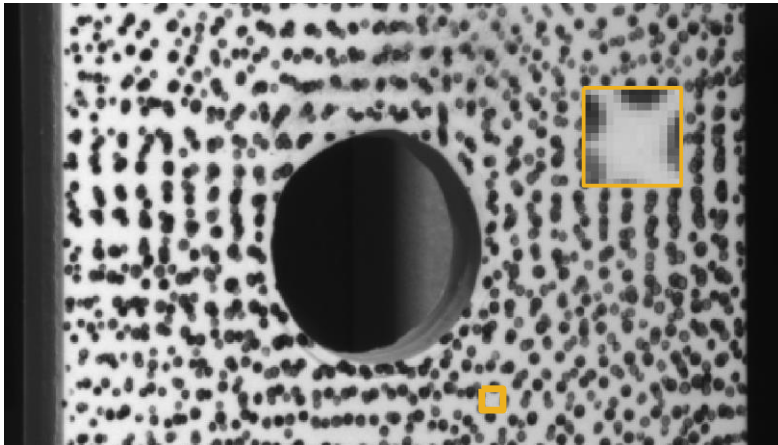
Step Size



## Correlation example: Subset

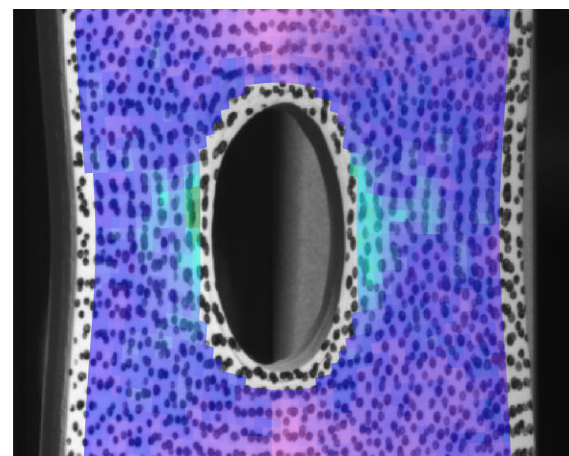
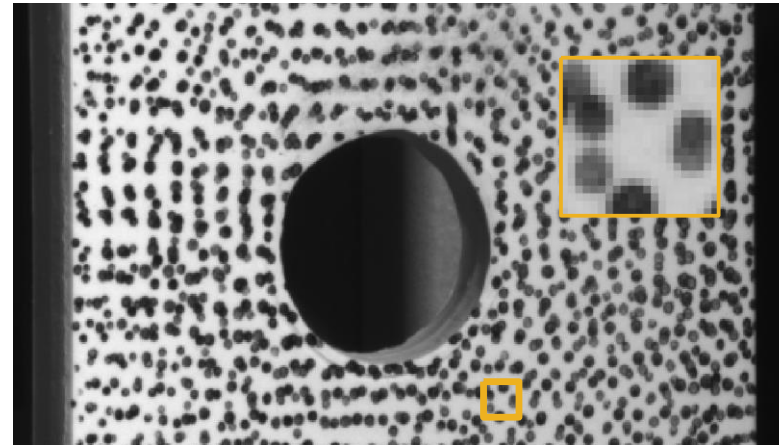
### Subset size = 13 px

- Too small
- Insufficient number of features
- High correlation residual
- Many uncorrelated points



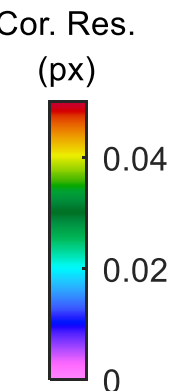
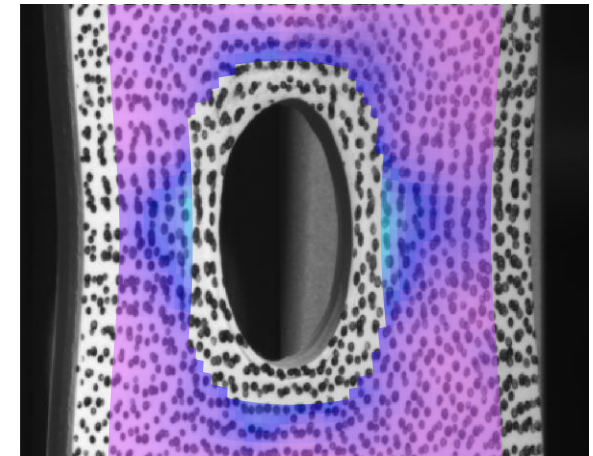
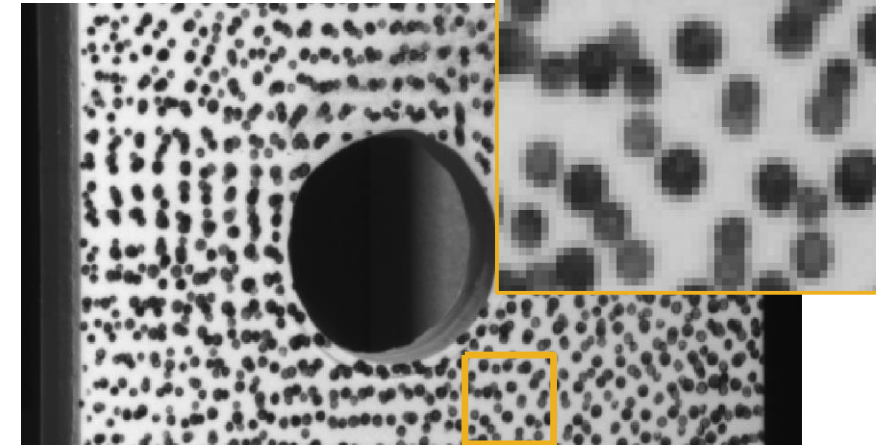
### Subset size = 21 px

- Reasonable size
- Sufficient number of features
- Low correlation residual
- No uncorrelated points



### Subset size = 51 px

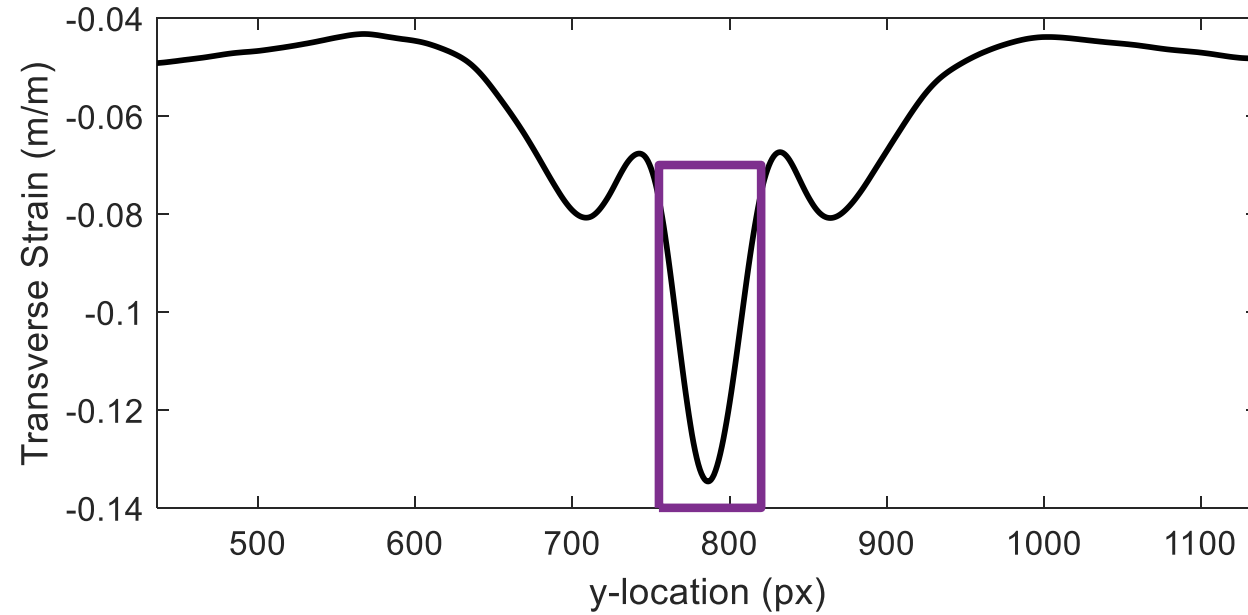
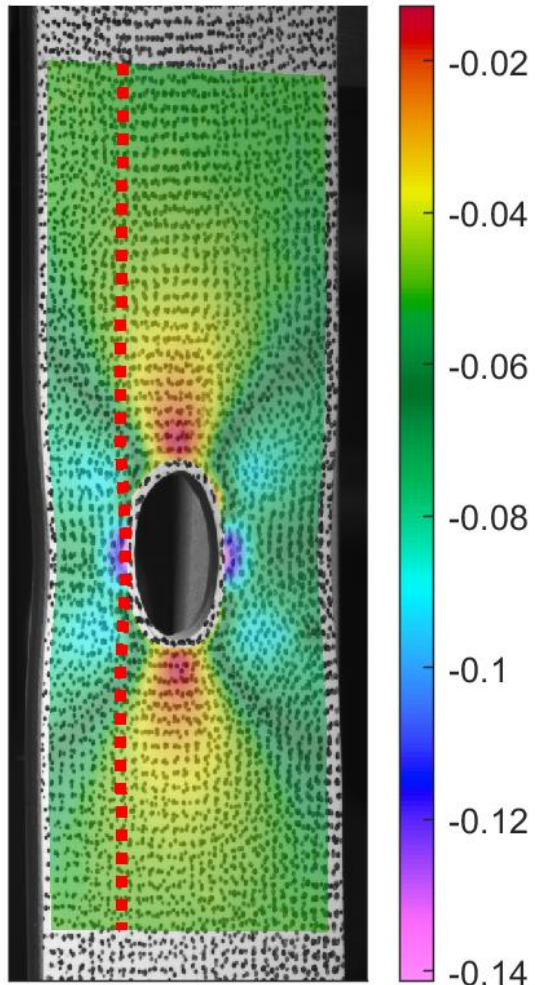
- Too large
- Large border of missing data near edges of ROI



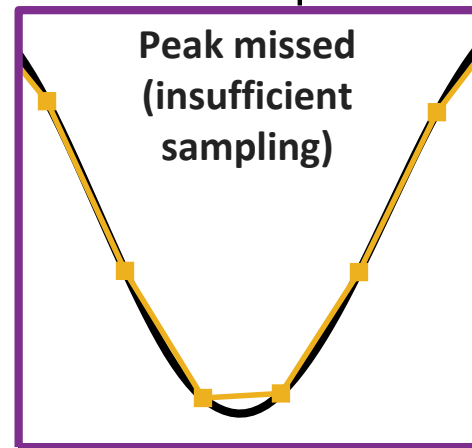


## Correlation example: Step size

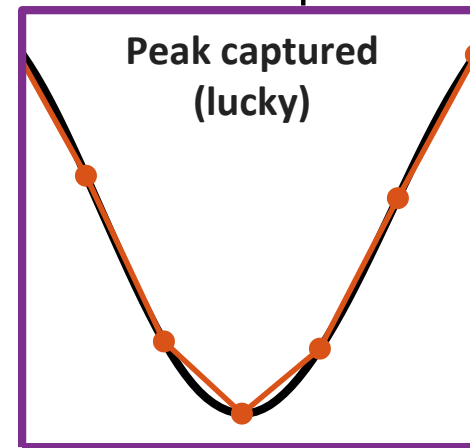
Transverse Strain (m/m)



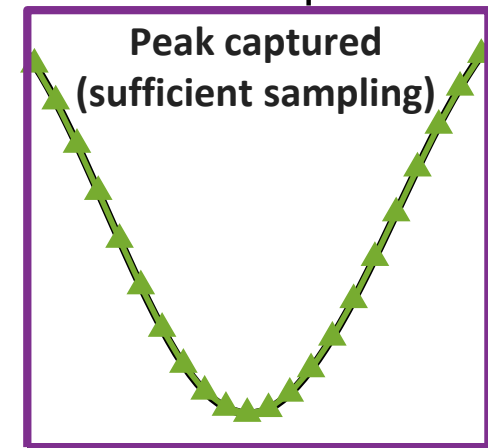
Step size 11 px  
Offset 7 px



Step size 11 px  
Offset 0 px



Step size 3 px  
Offset 0 px



# Thresholds

## Sec. 5.2.7

- ▶ Determine the quality and confidence of the displacement results
- ▶ Two main thresholds
  - ▶ Value of the matching criterion
  - ▶ Value of the epipolar error
- ▶ Software dependent

